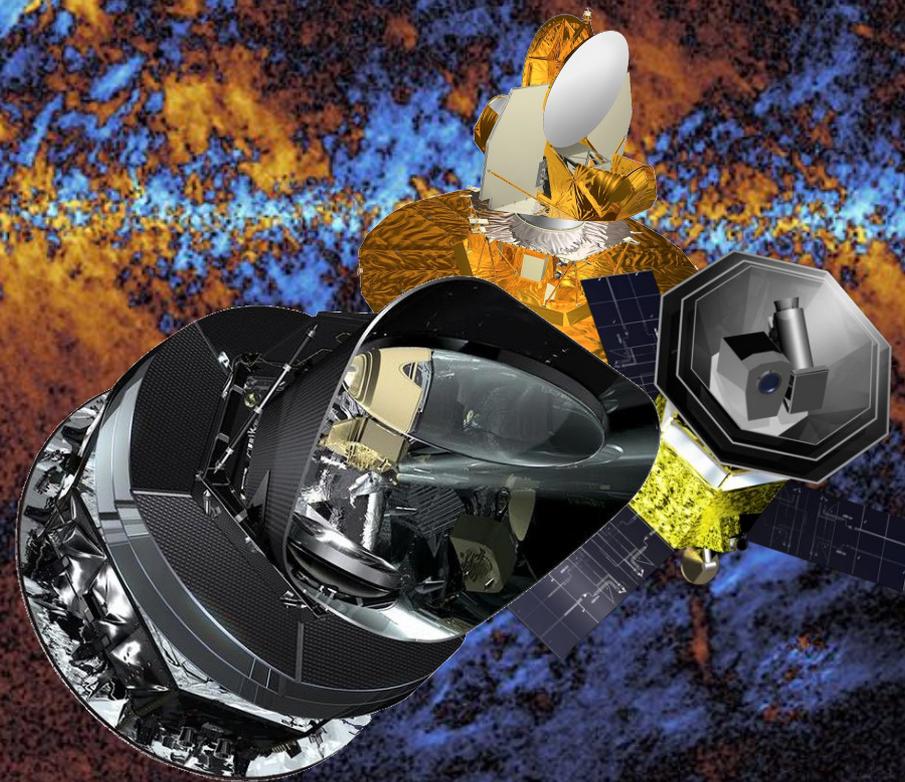


Calibration

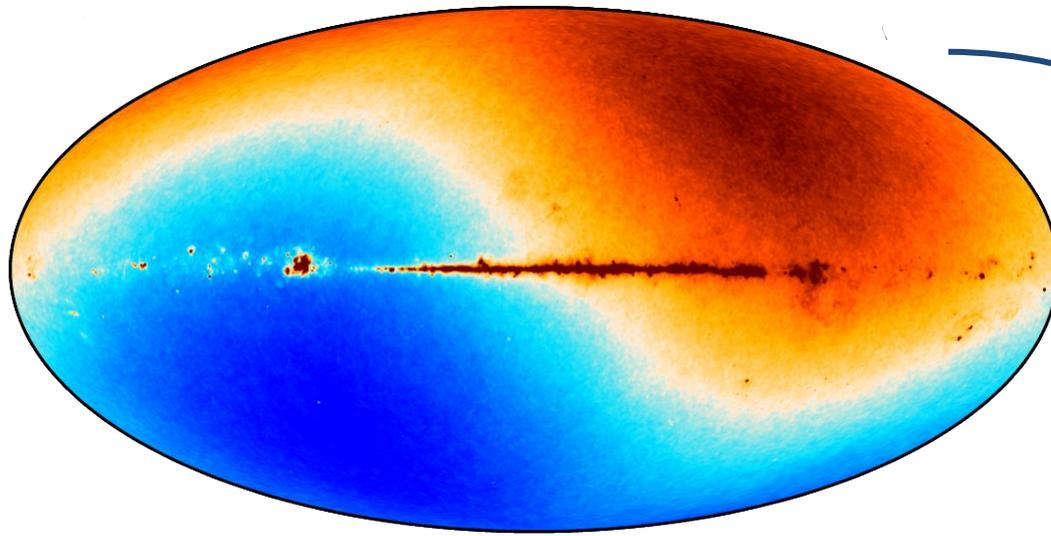
Eirik Gjerløw



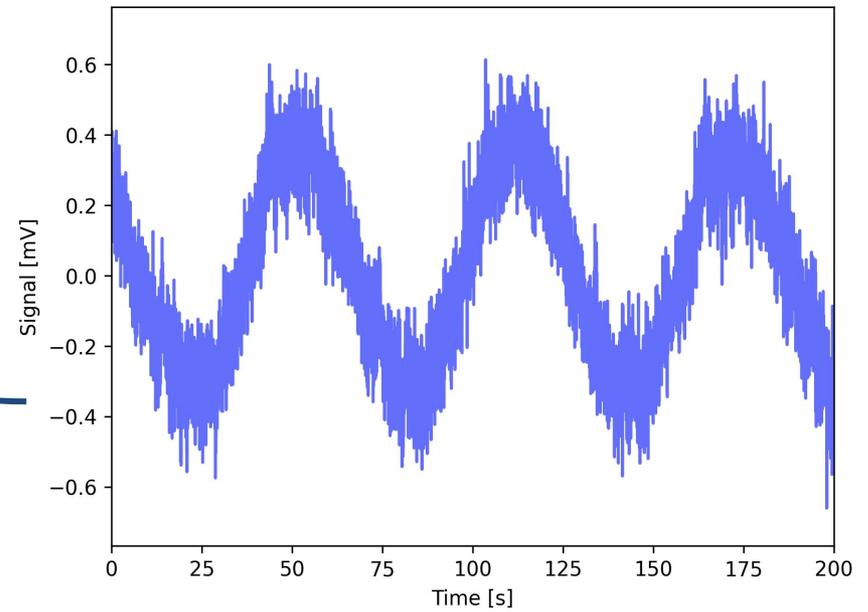
BeyondPlanck online release conference, November 18-20, 2020

This project has received funding from the European Union's Horizon 2020 research and innovation programme under grant agreement No 776282

What is calibration?



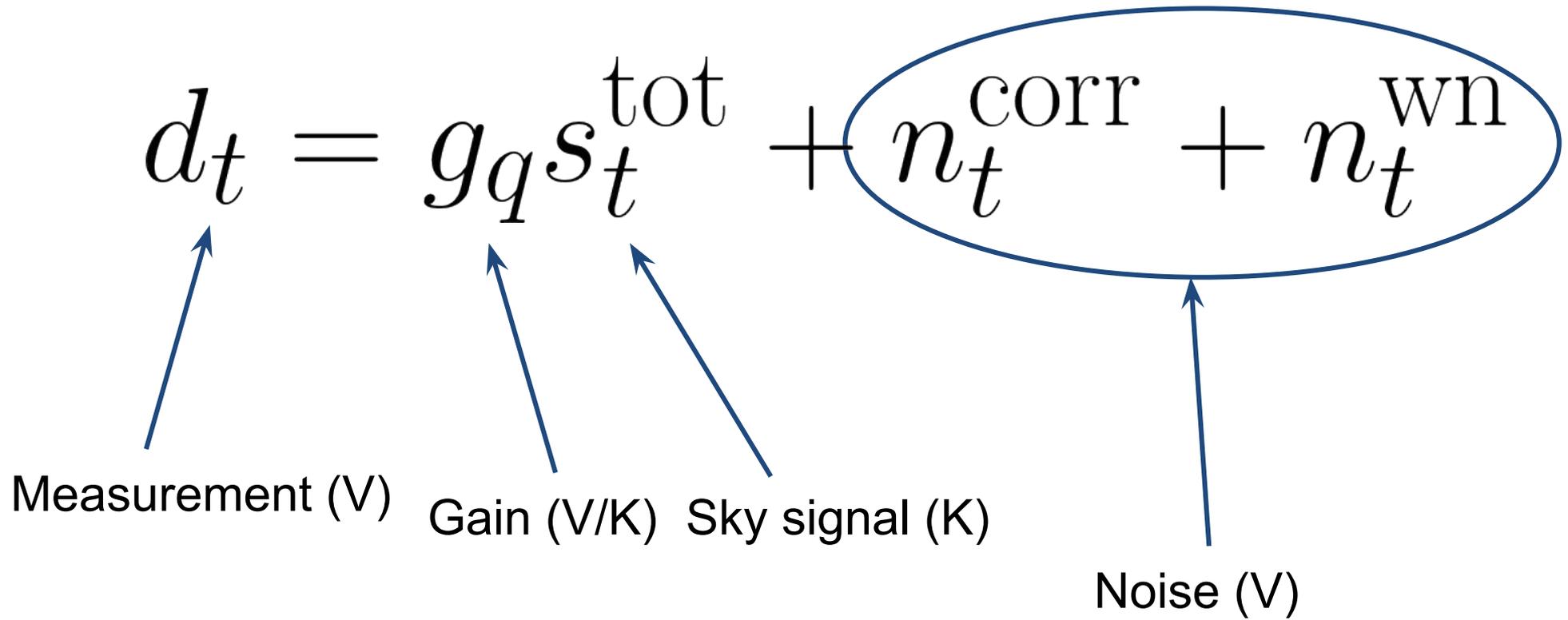
g



g^{-1}

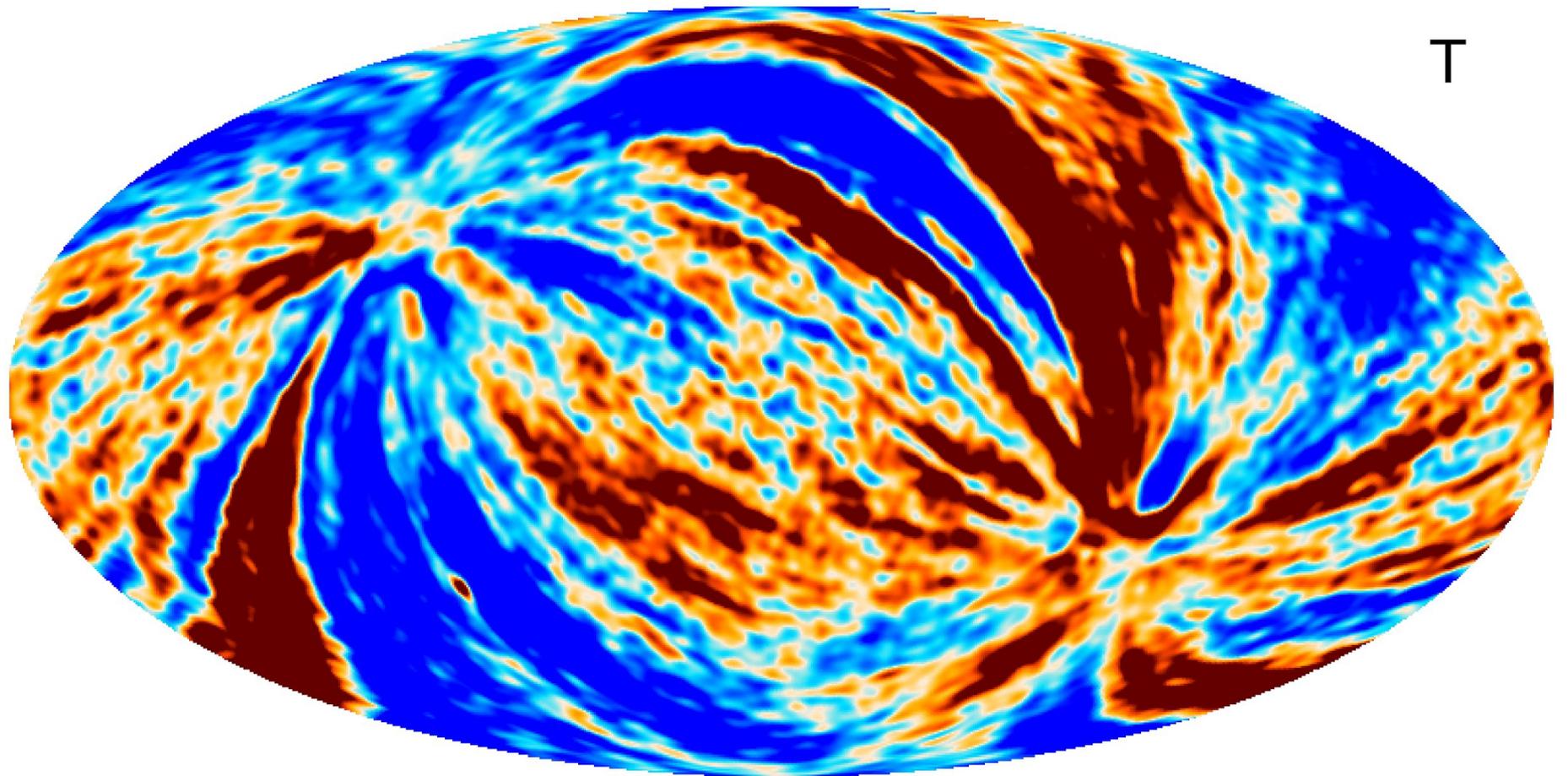
$$d_t = g_q s_t^{\text{tot}} + n_t^{\text{corr}} + n_t^{\text{wn}}$$

Measurement (V) Gain (V/K) Sky signal (K) Noise (V)



The diagram shows the equation $d_t = g_q s_t^{\text{tot}} + n_t^{\text{corr}} + n_t^{\text{wn}}$. Blue arrows point from the labels 'Measurement (V)', 'Gain (V/K)', and 'Sky signal (K)' to the variables d_t , g_q , and s_t^{tot} respectively. A blue oval encircles the noise terms $n_t^{\text{corr}} + n_t^{\text{wn}}$, with an arrow pointing from the label 'Noise (V)' to this oval.

Correlated noise-gain degeneracy

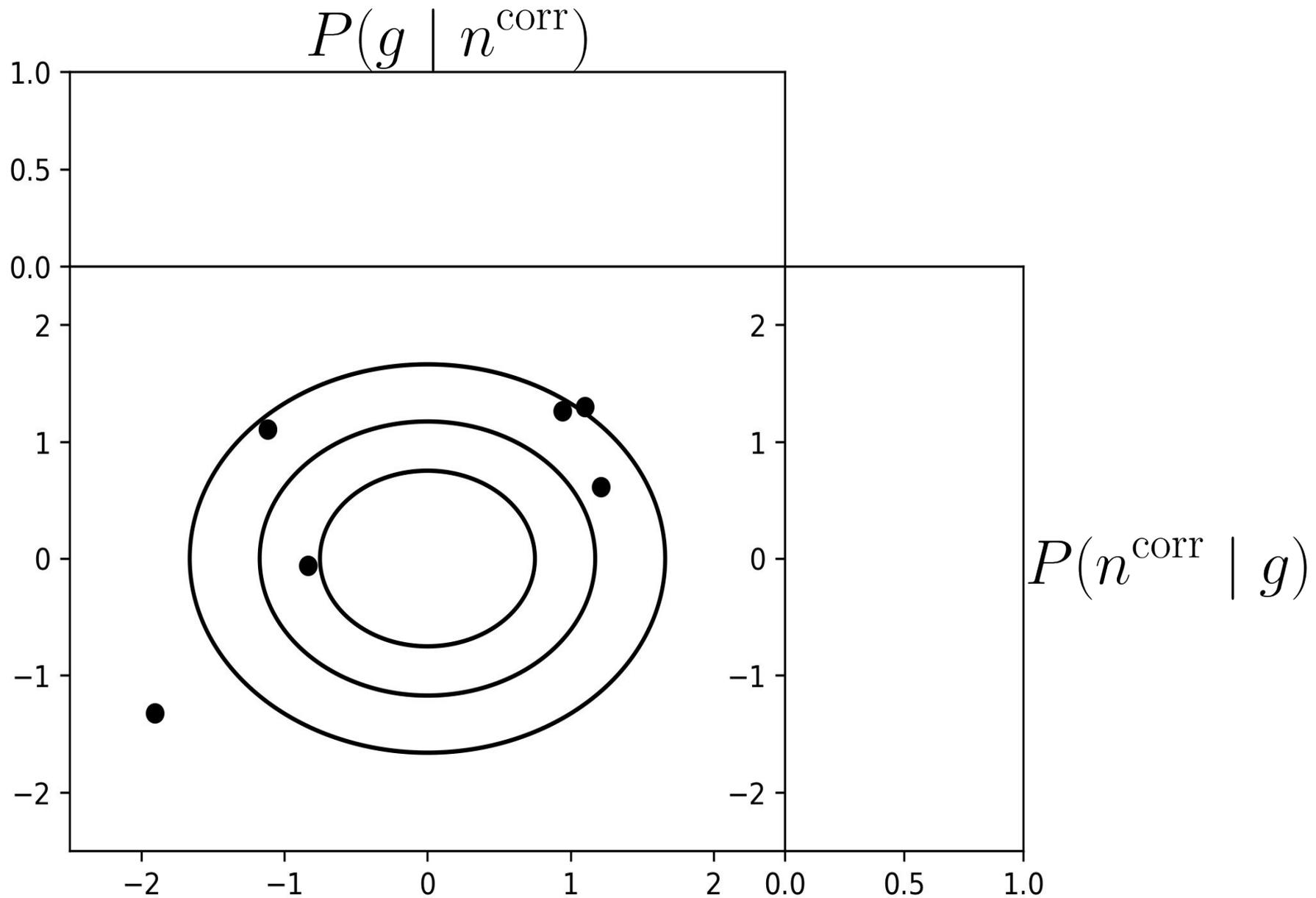


$$P(g, s^{\text{tot}}, n^{\text{corr}}, \dots | d)$$



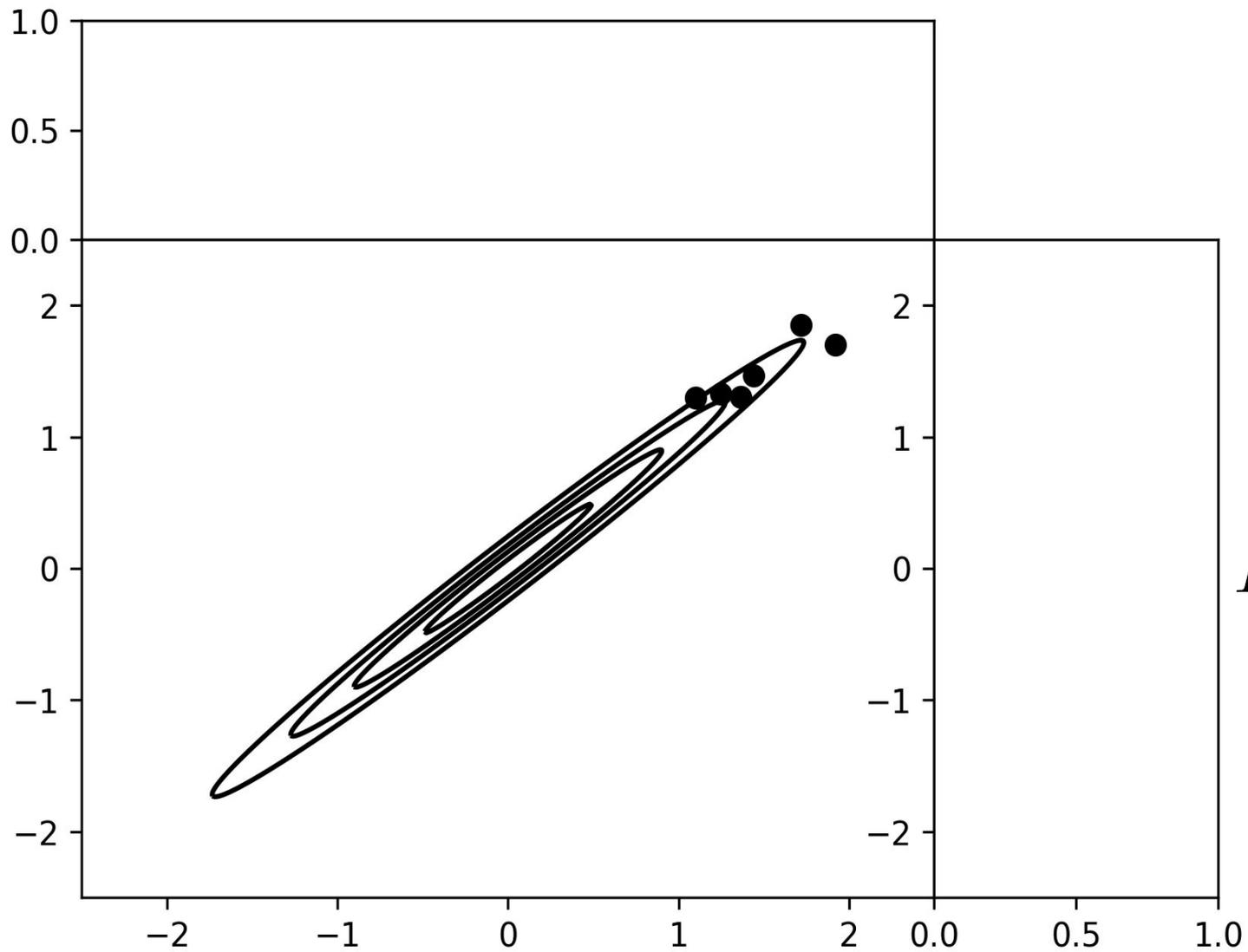
$$P(g | \mathcal{H}, (g^{\text{tot}}, n^{\text{corr}}), \dots)$$

Sampling from conditional distributions



Sampling from conditional distributions

$$P(g \mid n^{\text{corr}})$$



$$P(g, s^{\text{tot}}, n^{\text{corr}}, \dots | d)$$

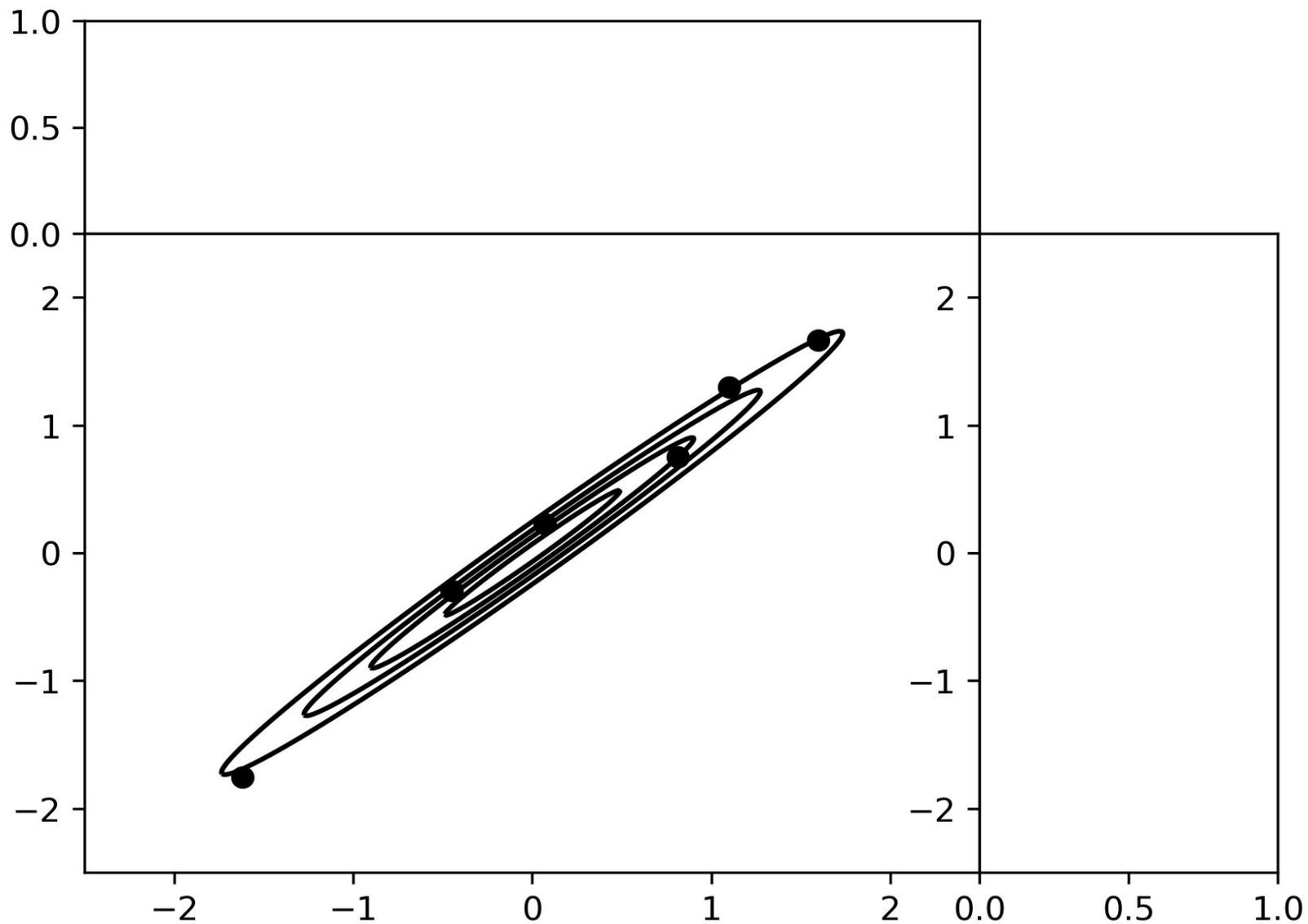

$$\text{---} P(g | n^{\text{corr}}) \text{---}$$


$$P(g, n^{\text{corr}}) = P(g)P(n^{\text{corr}} | g)$$

Sampling from the joint distribution



$$P(g)$$



$$P(n^{\text{corr}} | g)$$

Absolute calibration:

- Estimating the “true” value of the gain.
- Important for correctly estimating the total intensity emitted.

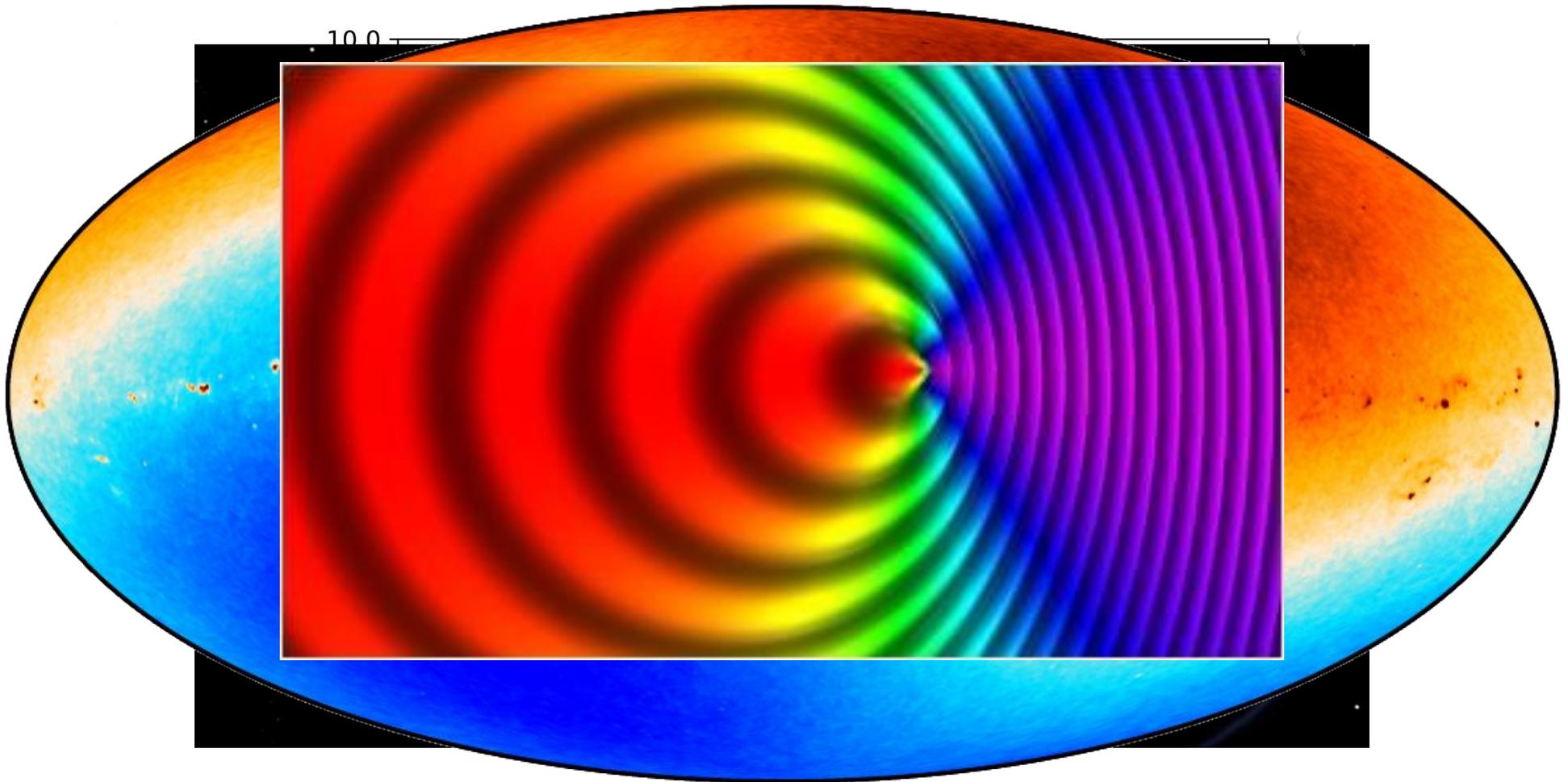
Relative calibration:

- Estimating the gain factor of one detector relative to another.
- Important for reconstruction of the polarization signal.
- Requires a much higher accuracy than absolute calibration.

Calibration sources

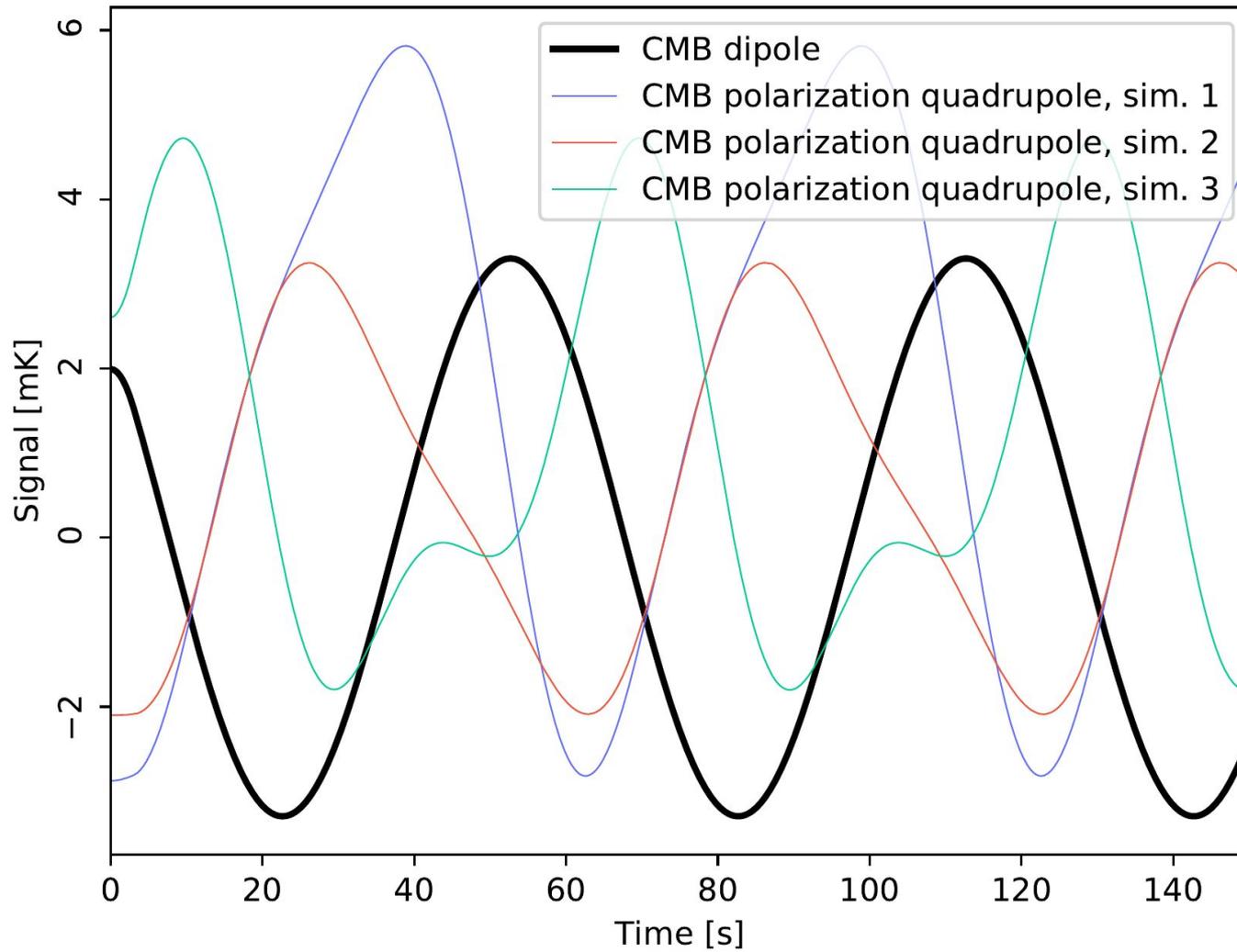


$$d_t = g_q s_t^{\text{tot}} + n_t^{\text{corr}} + n_t^{\text{wn}}$$



Attr: en:TxAlien - en:Image:Velocity0.70c.jpg, CC BY-SA 3.0,
<https://commons.wikimedia.org/w/index.php?curid=1066460>

The polarization quadrupole



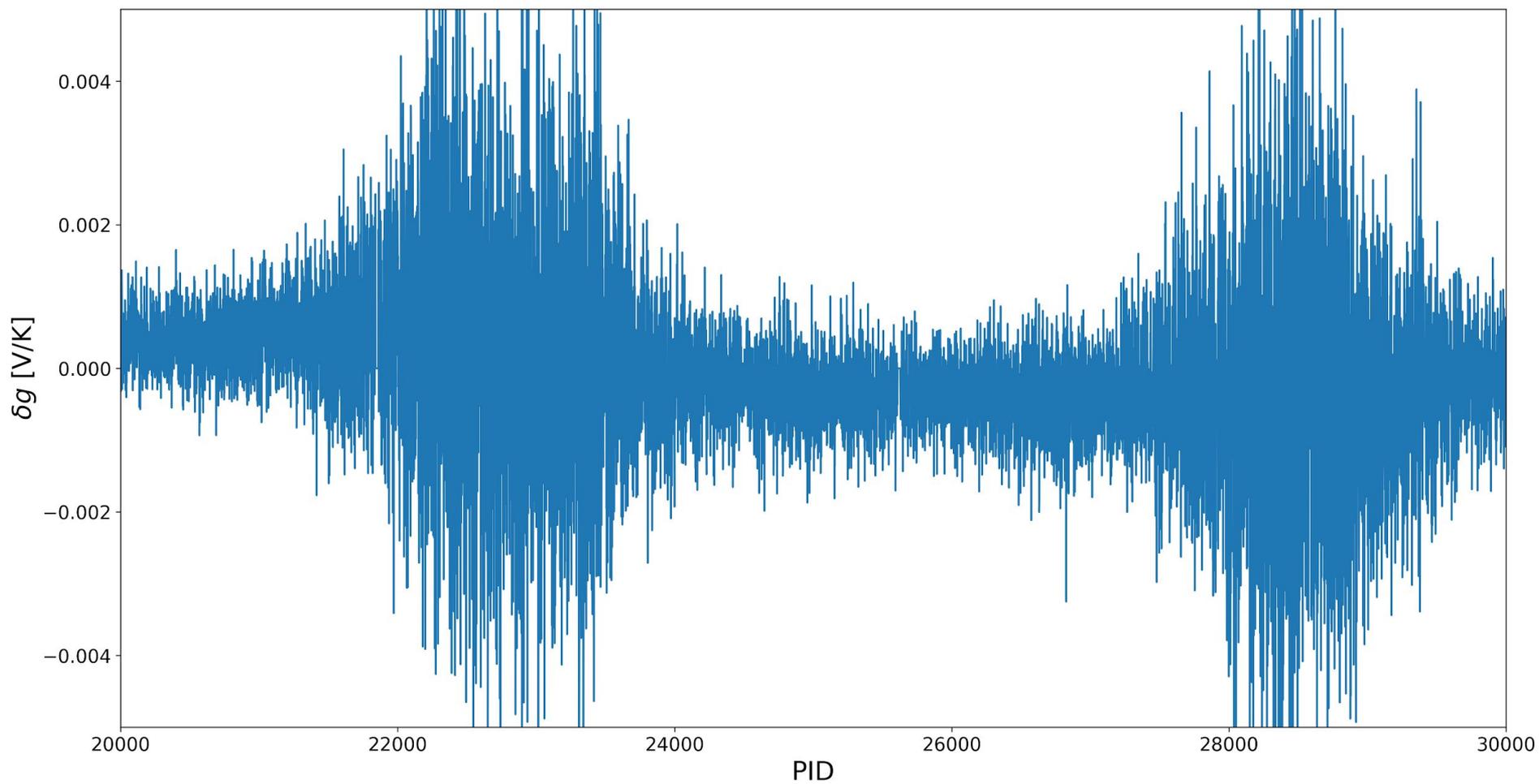
$$g_{q,i} = g_0 + \Delta g_i + \delta g_{q,i}$$

To be estimated using
the orbital dipole

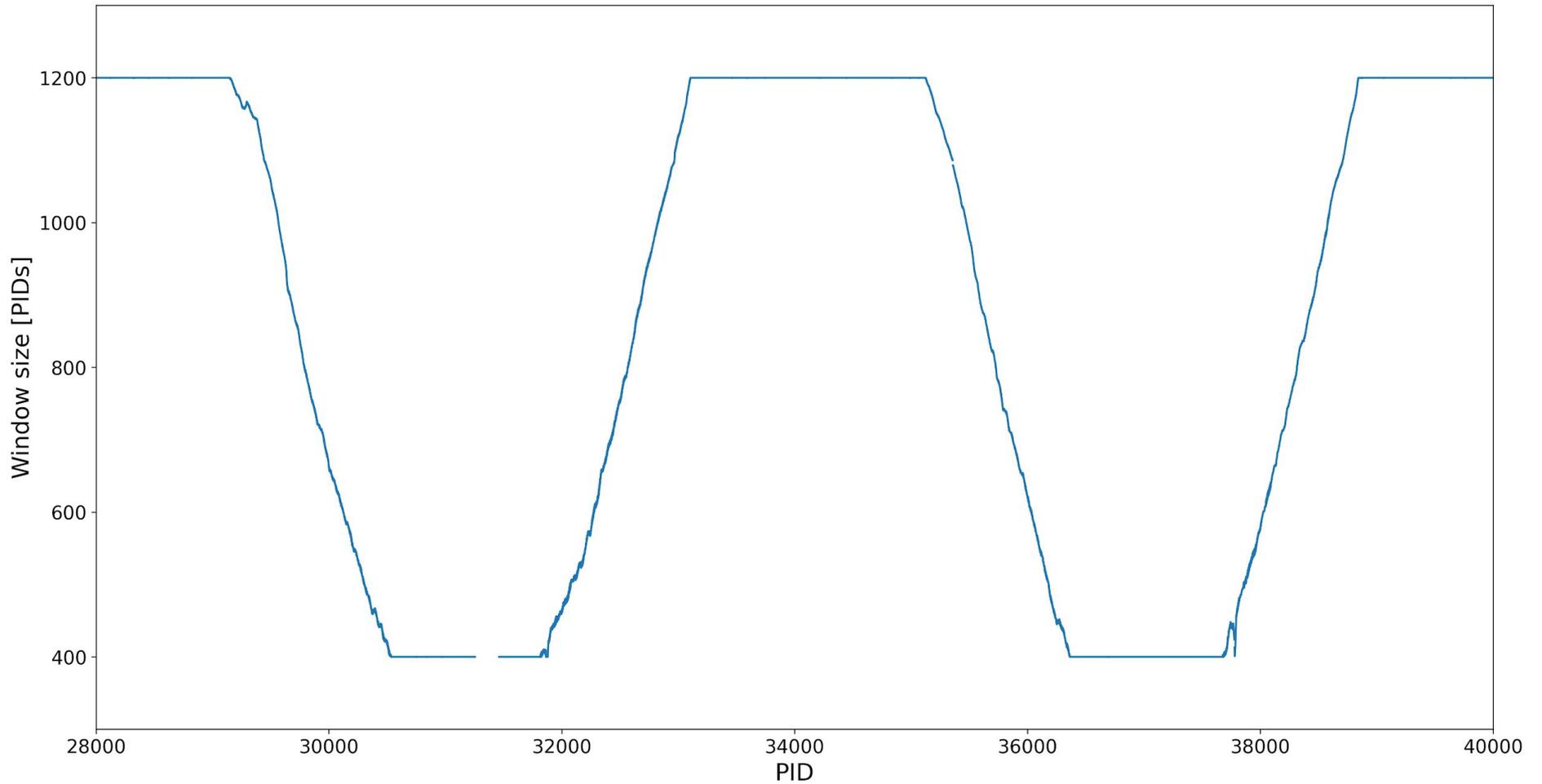
To be estimated using the full signal

$$\sum_i \Delta g_i = 0 \quad \text{and} \quad \sum_q \delta g_{q,i} = 0$$

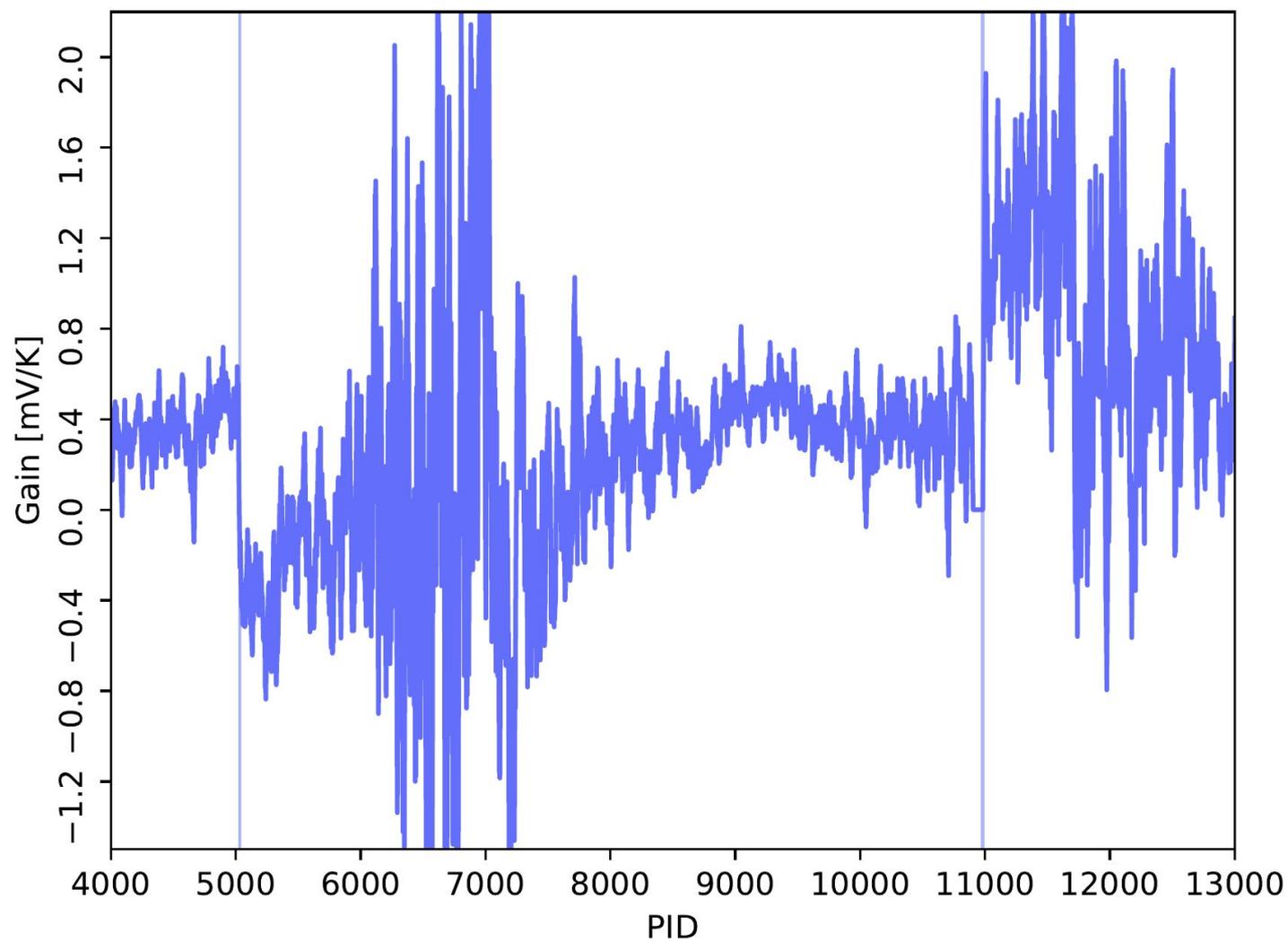
Smoothing the time variable gain



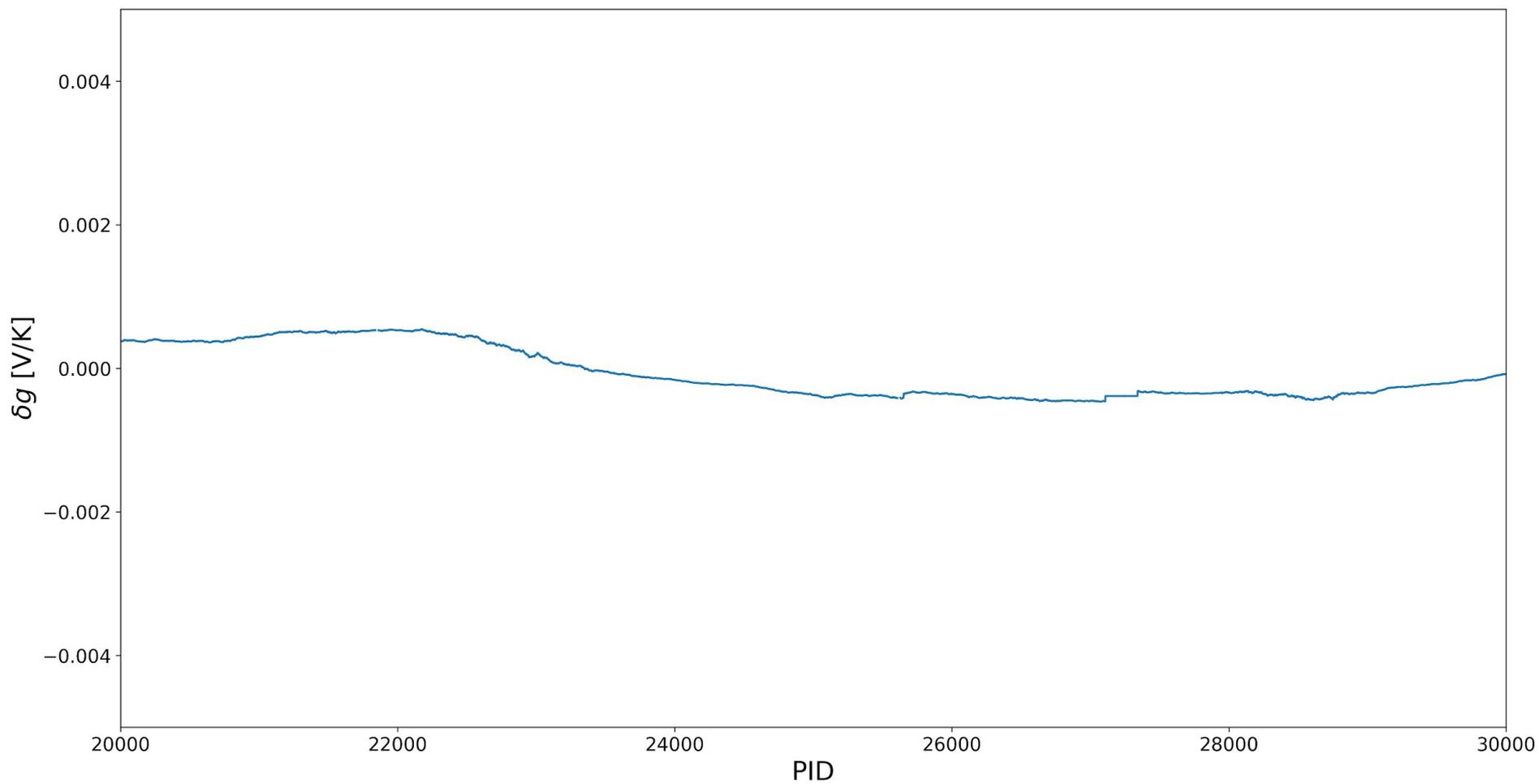
Smoothing the time variable gain



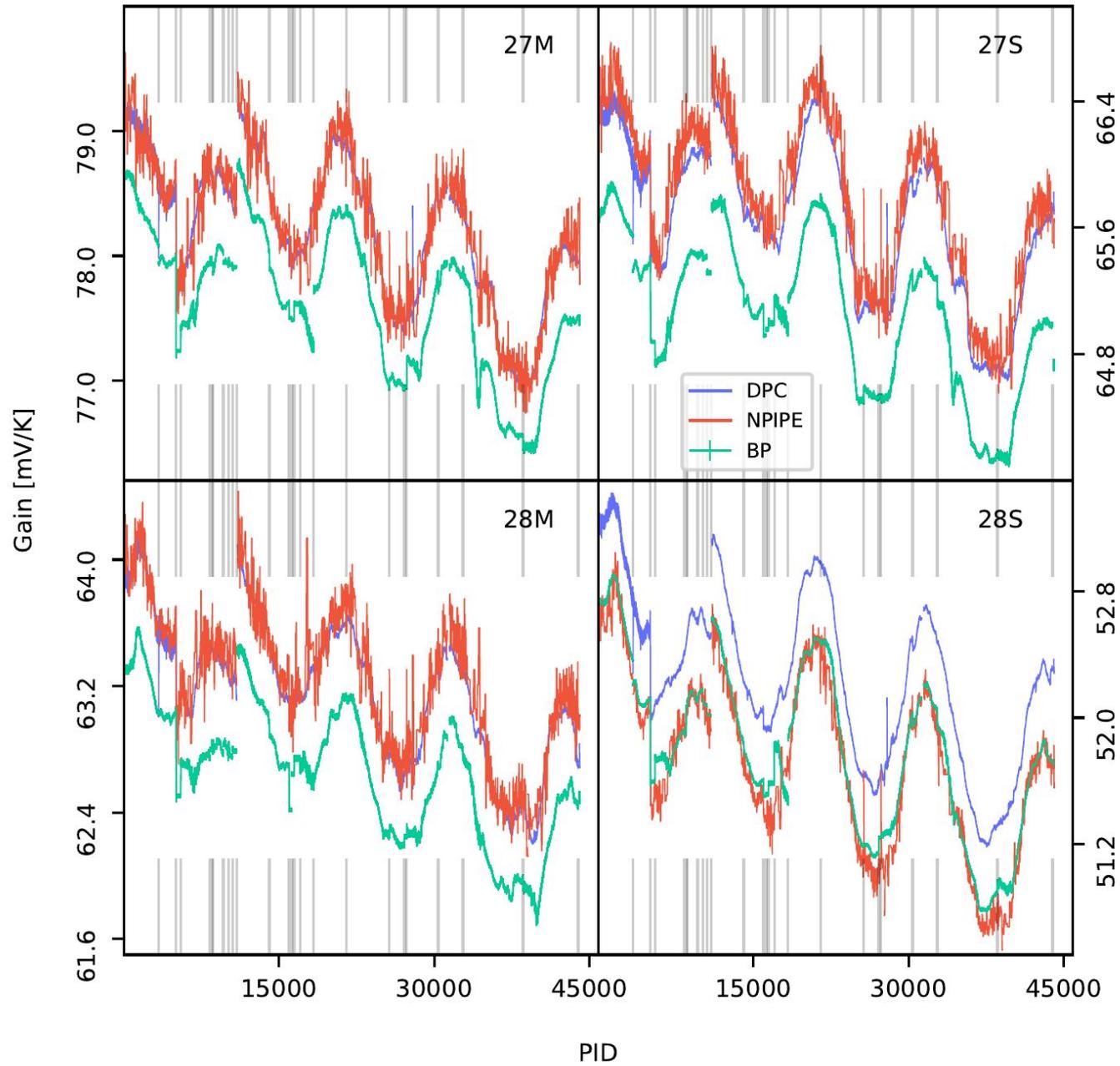
Gain jumps



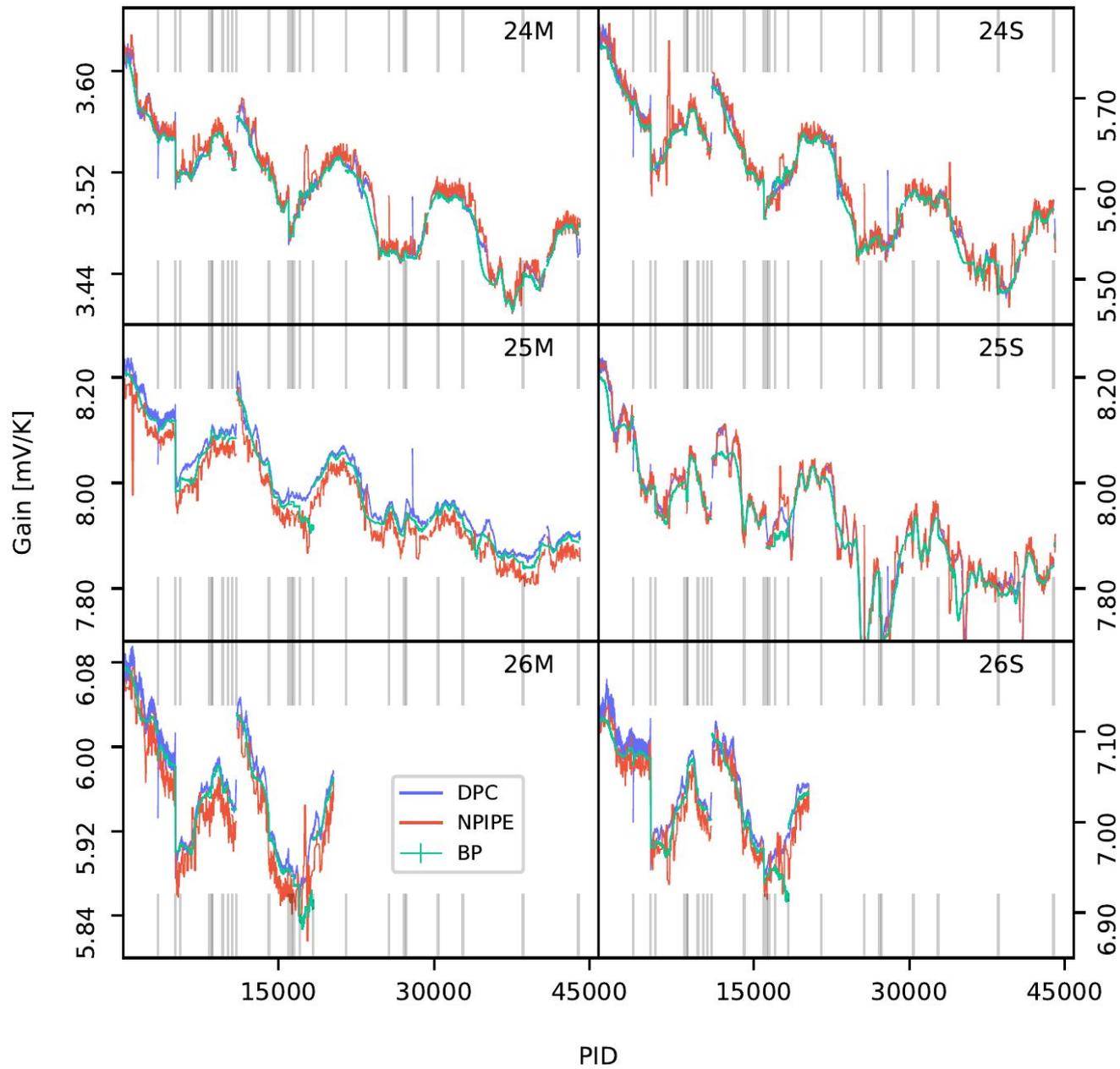
Smoothing the time variable gain



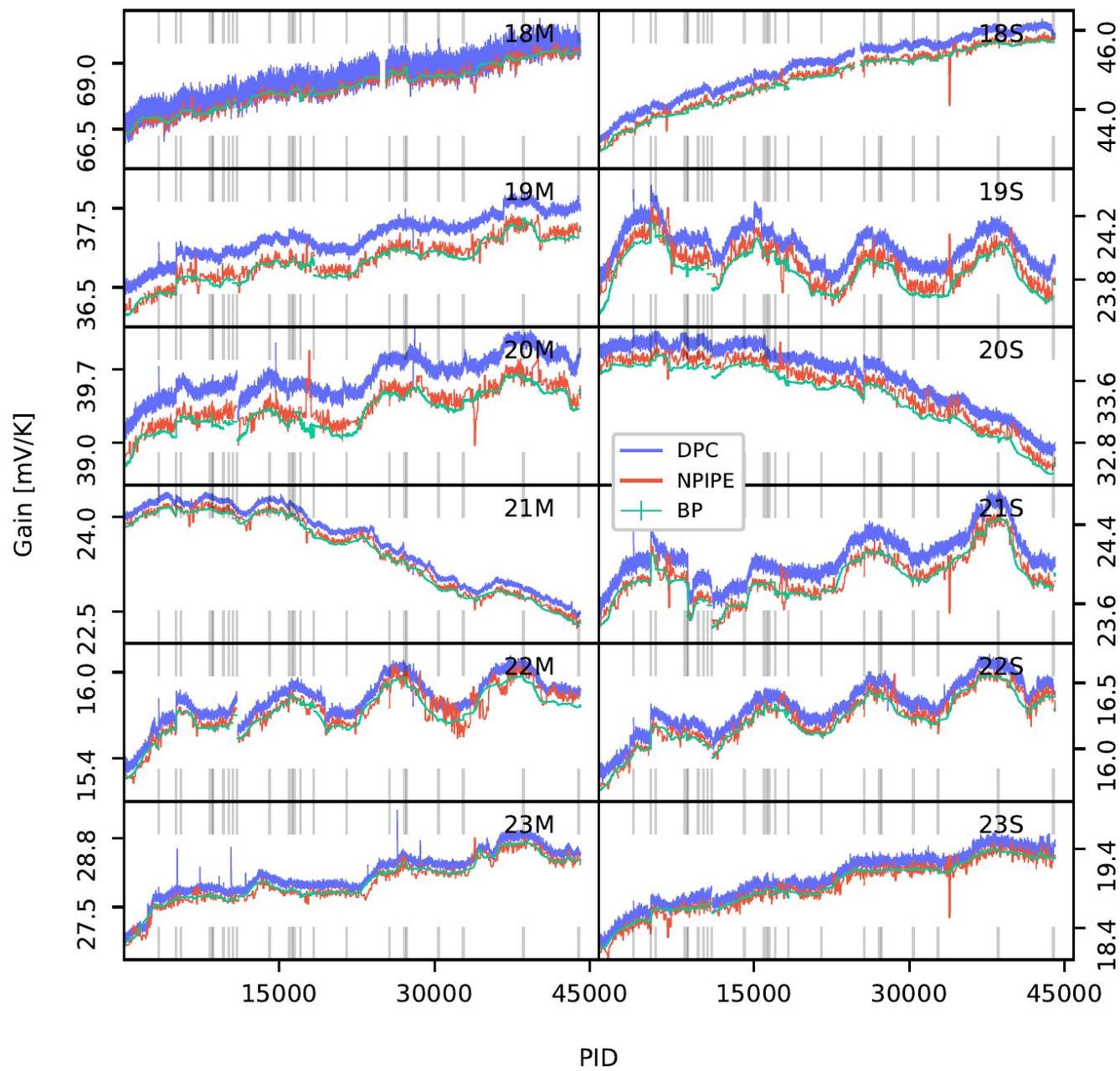
Results



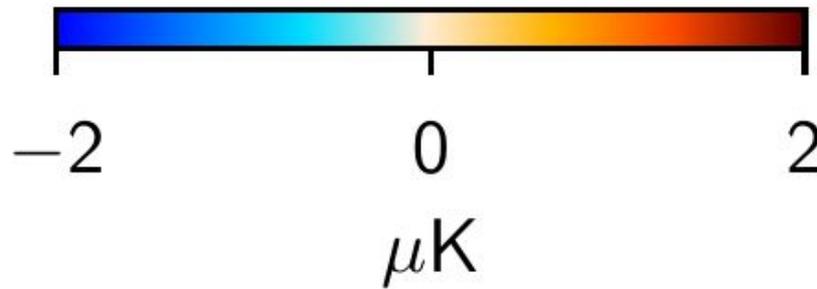
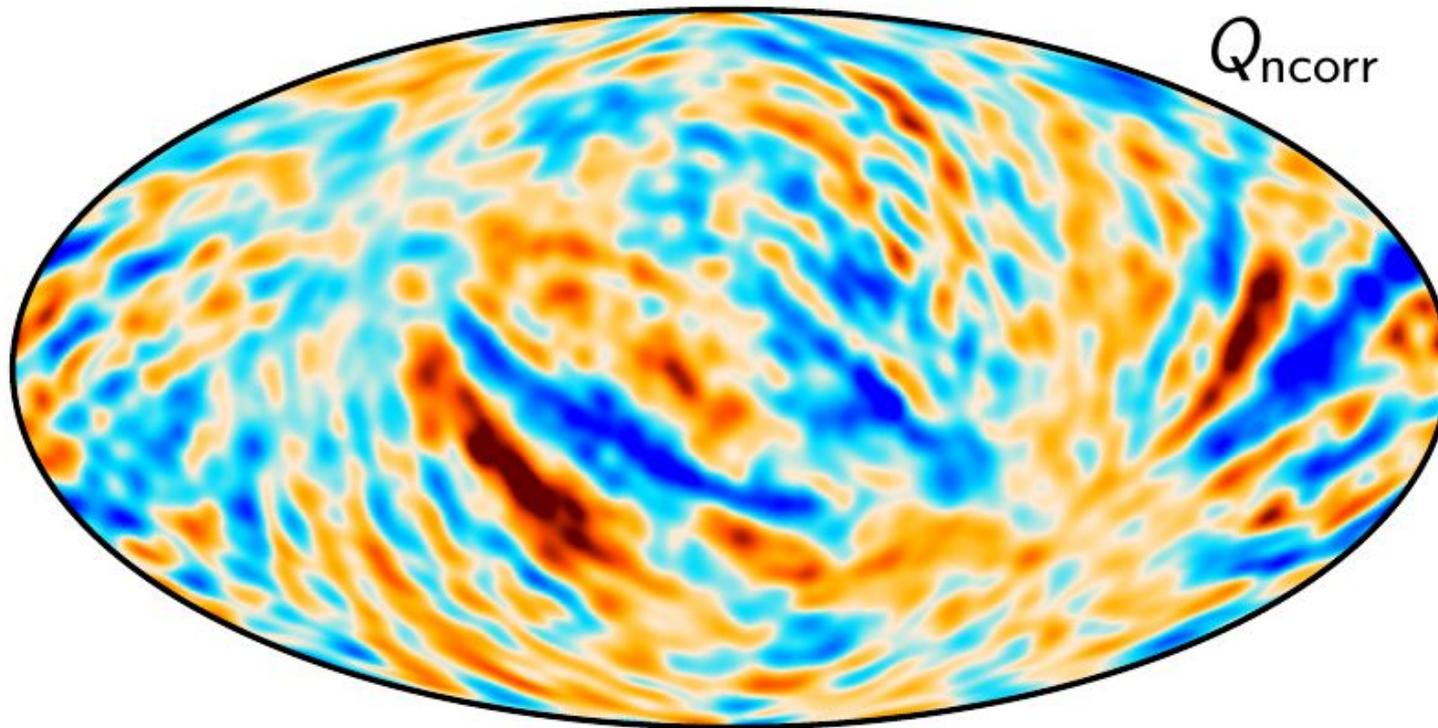
Results



Results



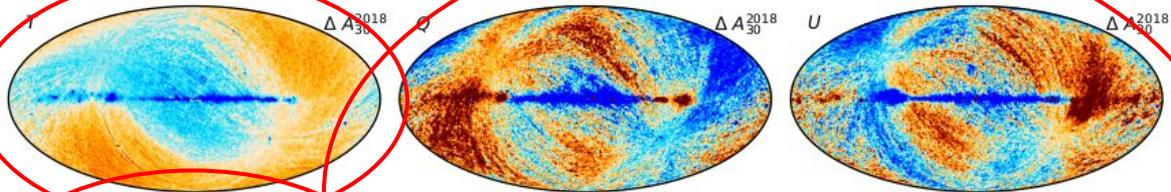
Correlated noise stripes



BP and other pipelines

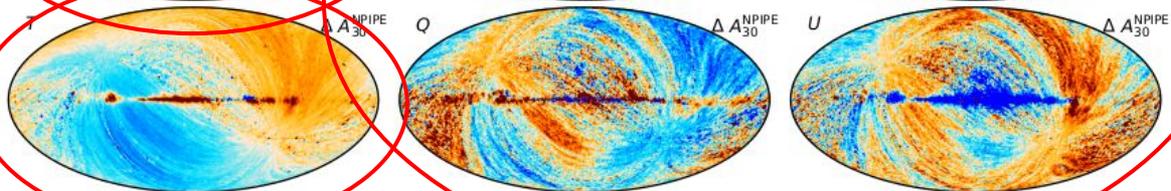


BP-DPC

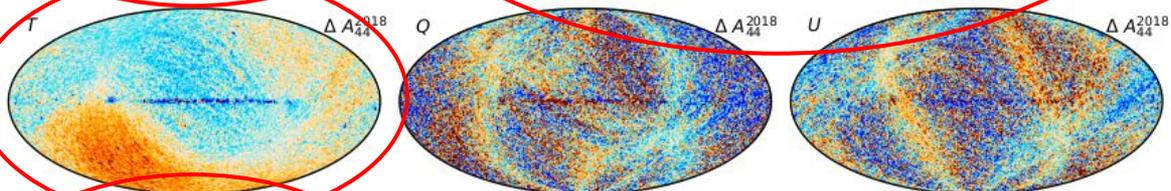


30 GHz

BP-NPIPE

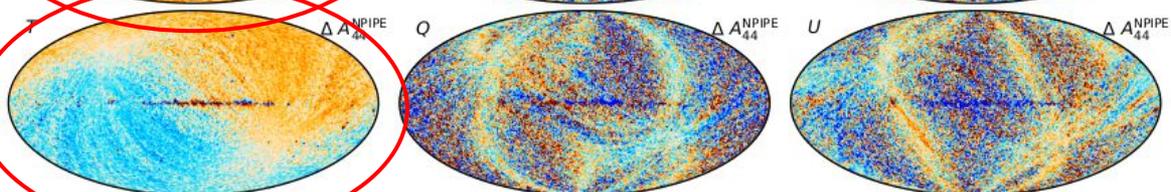


BP-DPC

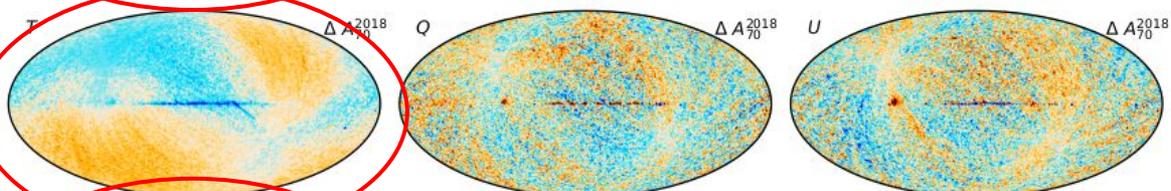


44 GHz

BP-NPIPE

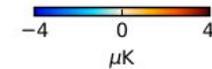
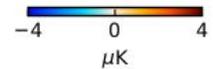
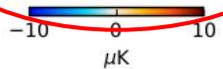
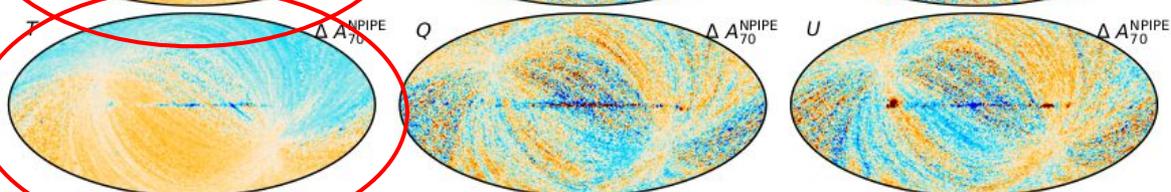


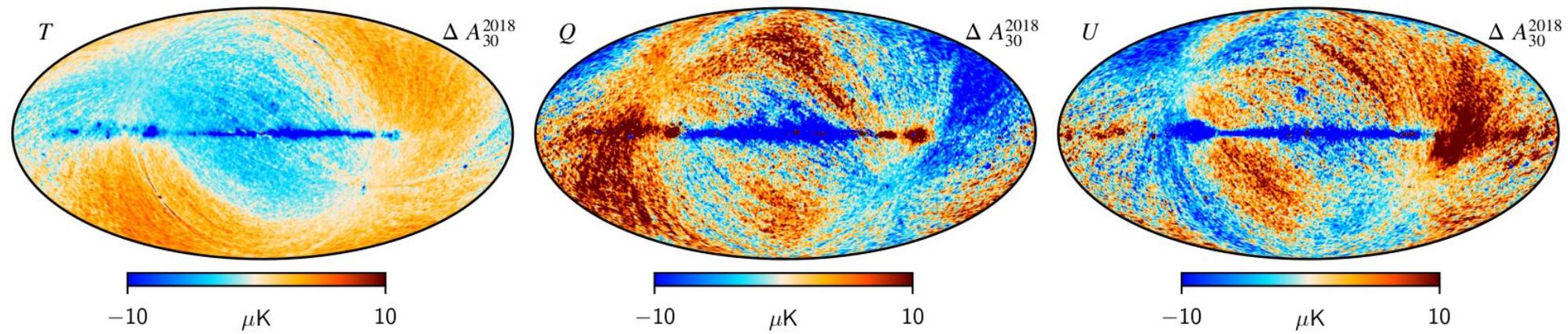
BP-DPC



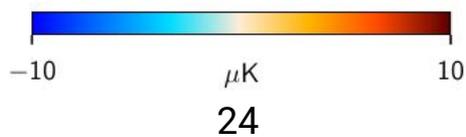
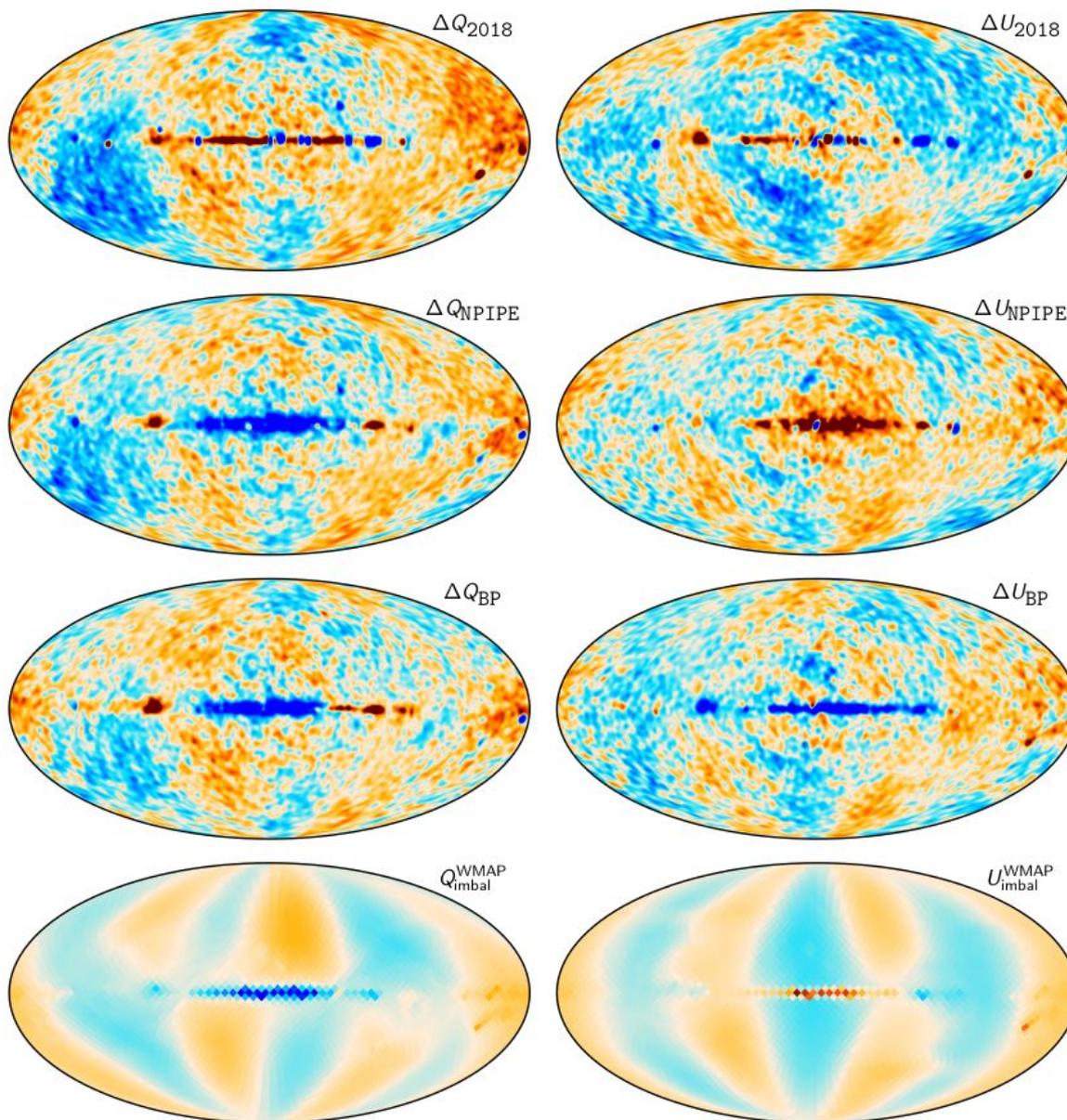
70 GHz

BP-NPIPE

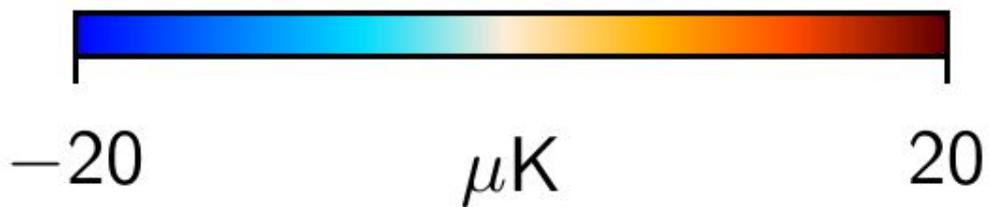
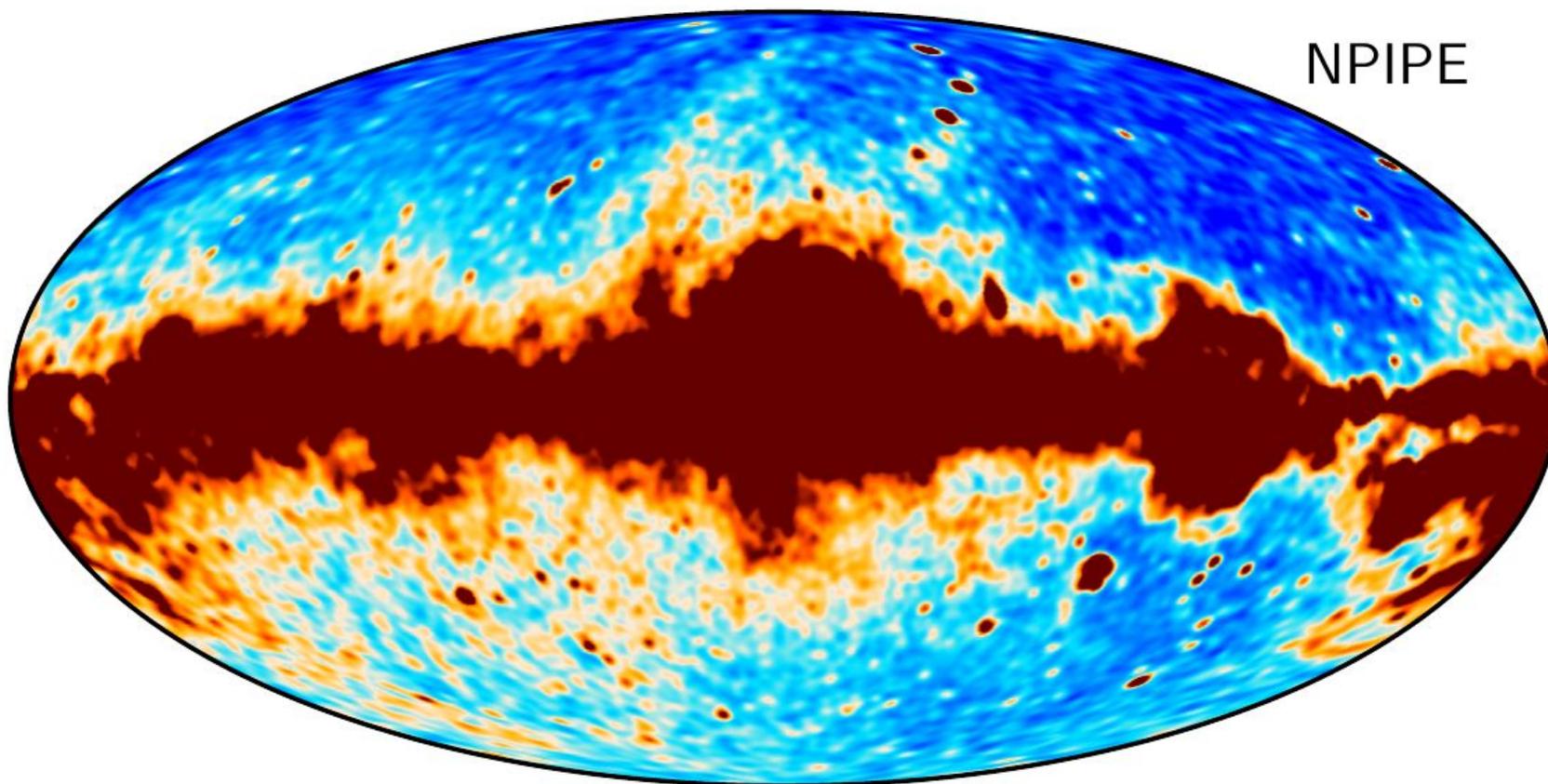




WMAP differences



Difference between 70 GHz and 44 GHz



- A working calibration solution, sampled jointly with correlated noise and sky signal.
- Certain differences from previous pipelines, especially for 30 GHz.
- Some residual problems with correlated noise stripes, to be investigated further.
- Overall better fit to WMAP polarization data - and should become even better with WMAP time-domain data included.

This project has received funding from the European Union's Horizon 2020 research and innovation programme under grant agreement No 776282



- “*BeyondPlanck*”
 - COMPET-4 program
 - PI: Hans Kristian Eriksen
 - Grant no.: 776282
 - Period: Mar 2018 to Nov 2020

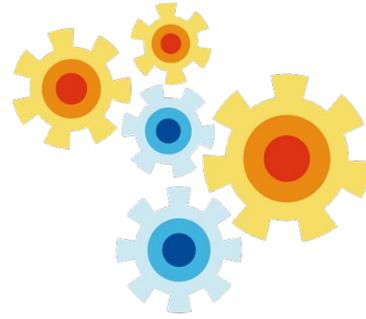
Collaborating projects:

- “*bits2cosmology*”
 - ERC Consolidator Grant
 - PI: Hans Kristian Eriksen
 - Grant no: 772 253
 - Period: April 2018 to March 2023
- “*Cosmoglobe*”
 - ERC Consolidator Grant
 - PI: Ingunn Wehus
 - Grant no: 819 478
 - Period: June 2019 to May 2024

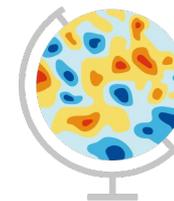
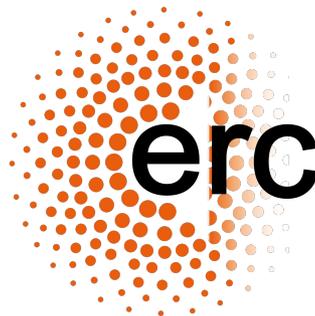


Questions?

Beyond PLANCK



Commander



Cosmoglobe Beyond PLANCK